

Dr. Henry McDonald

Director

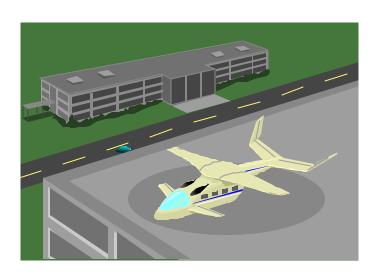
NASA Ames Research Center



Rotorcraft Vision

True point-to-point or door-to-door transport

- ✓ Complete flexibility of origin and destination
- ✓ No need for extensive real estate or large infrastructure investment
- ✓ No constraints on system throughput dictated by the need for runways





3-D Grid Transportation System





Runway Independent Aircraft Operations



Increases airport throughput by 25% and reduces delays at airports

 Provides 50% as much delay reduction as a new runway



- Separate corridors and runway traffic for slower aircraft and jet transports
- Improved separation in departure corridors

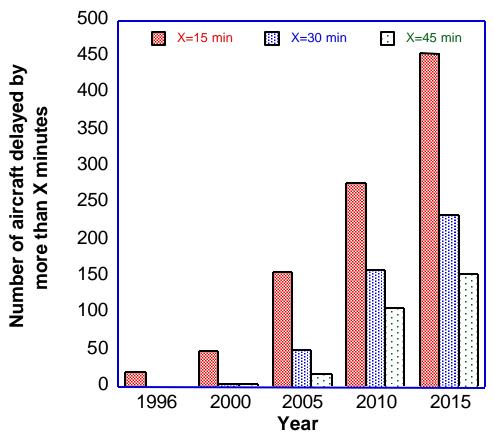


Commuter fixed wing aircraft (< 300 nm) carry 20% of the passengers, yet account for 40% of the departures at major hub airports



Flight Delays Will Worsen Without Corrective Action

Predicted Delay Increase at a Major Hub Airport Based on MITRE DPAT Model

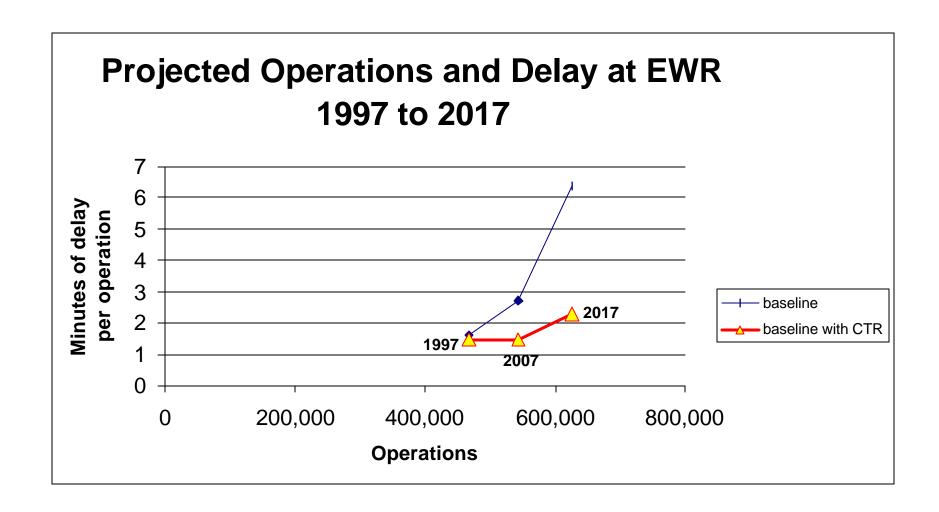


Single day, good weather
Single airport, major hub
Total landings
1996: 997
2000: 1,378
2005: 1,576
2010 1,776
2015: 1,910

Source: Donohue, G., "Investing in Air Transportation Research," *Aerospace America*, Sept. 2000, pp. 28-31



Impact of Runway Independent Operations

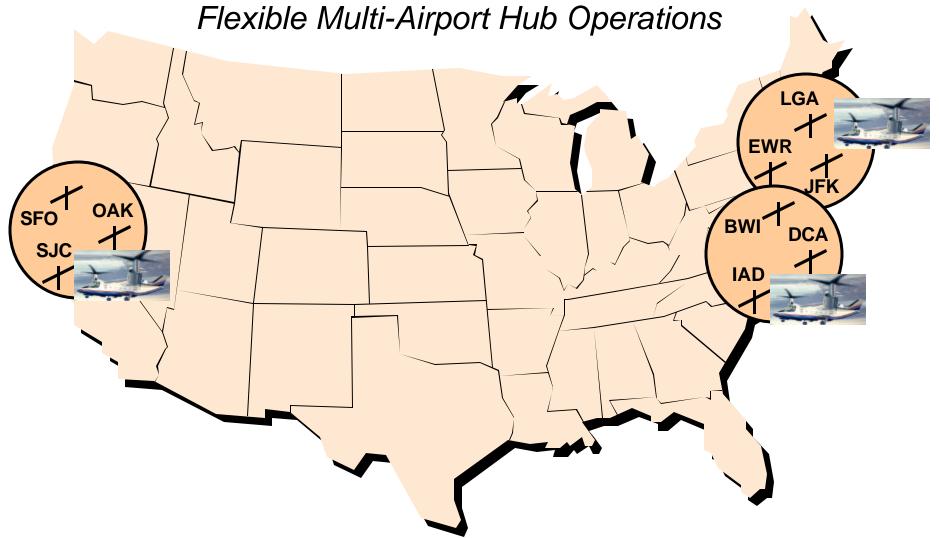


Source: Civil Tiltrotor (CTR) Feasibility Study - Impact at EWR



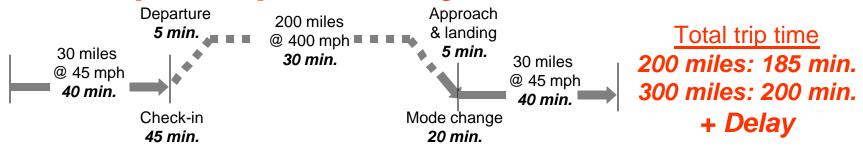
Virtual Hub Concept

Runway-Independent Aircraft Enable Flexible Multi-Airport Hub Operations

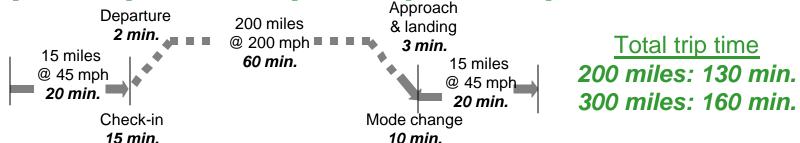


Rotorcraft Can Sharply Reduce Door-to-Door Time

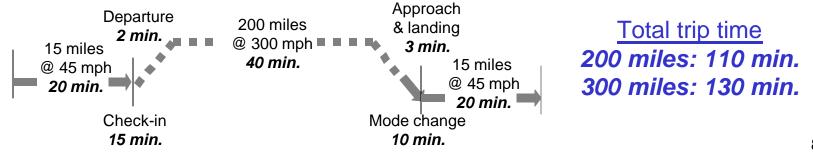
Airport to Airport (Fixed Wing)



GA Airport/Vertiport to GA Airport/Vertiport (Helicopter)



GA Airport/Vertiport to GA Airport/Vertiport (Tiltrotor)





Barriers to Achieving the Vision

Key Inhibitors to Expanded Rotorcraft Applications:

- ➤ Cost per Seat-Mile or Ton-Mile
- ➤ Community Acceptance
- > Reliable All-Weather Service
- Perceived Safety
- > Passenger Acceptance (Ride Comfort, Speed, etc.)
- Piloting Skill Required
- ➤ Infrastructure for 3-D Grid Operation



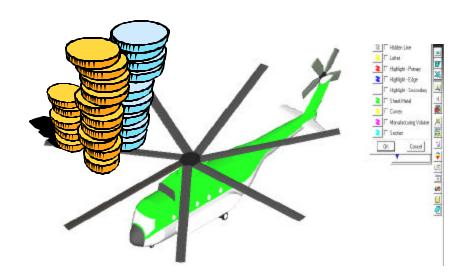
Effects of Technology Improvement

U.S. Army Future Transport Rotorcraft 20-ton Payload, 300-mile Mission Radius

<u>1994</u>

Gross Weight: 126 tons

Unit Flyaway Cost: \$186 mil.



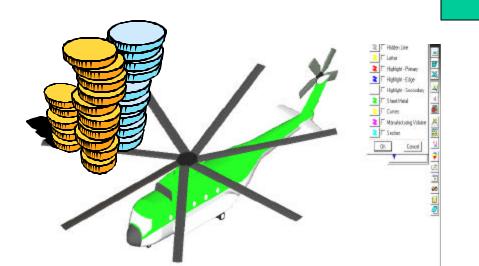
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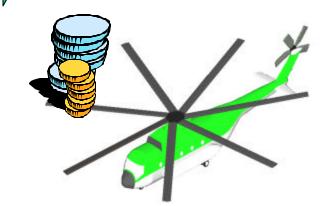
Unit Flyaway Cost: \$186 mil.



2005

62 tons (-51%)

\$74 mil. (-61%)



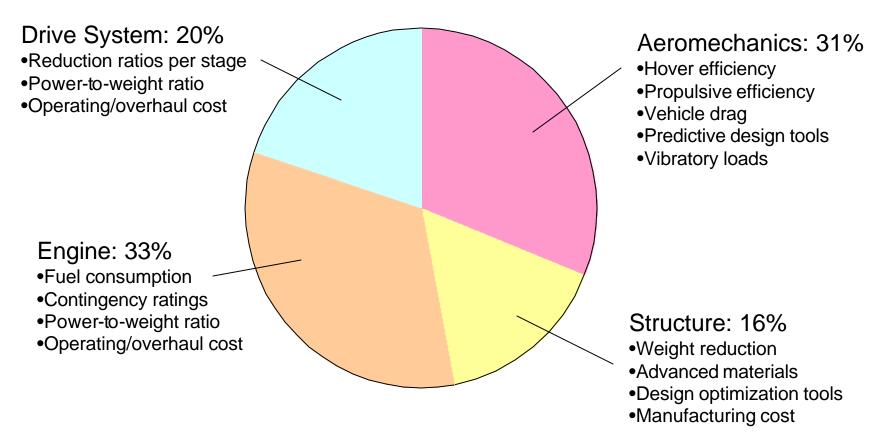
NASA .

Effects of Technology Improvement

Future Transport Helicopter

Percent gross weight/cost reduction by source

1994-2005

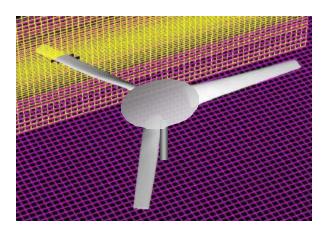




Advanced Rotor/Drive System Concepts

Continuous control of shape and airflow achieves near-ideal performance

- Smart material "morphing" blade geometry
 - Swashplate-less control
 - Lightweight rotor construction
 - Reverse velocity airfoils



- Active blowing and boundary layer modification
 - Active vibration and noise control
 - Low-noise geometry

- Super-safe rotor and drive shaft
- Variable speed, intelligent, self-reconfigurable drive system



Bio-Analogous Distributed Systems

Distributed sensors, processors, and actuation devices tailor drag and lift, counter vibration, diagnose faults, and implement corrective action





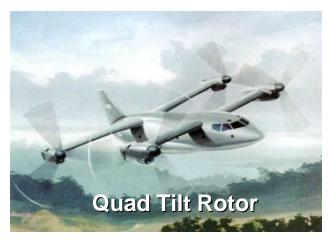
Distributed sensors, processors, and actuation devices

Self-monitoring, adaptive, reconfigurable, self-healing systems



Advanced Vehicle Configurations

High speed enhances productivity of piloted and uninhabited rotorcraft











Personal Transport "Crashproof" Rotorcraft

UAV technology and smart systems enhance safety and reliability

Environmentally friendly

Low-noise rotor

Economical

- Low-cost construction
- Affordable propulsion system



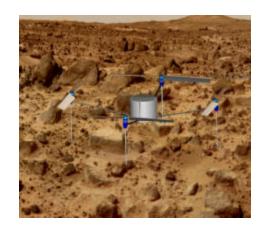
Safe and easy to operate

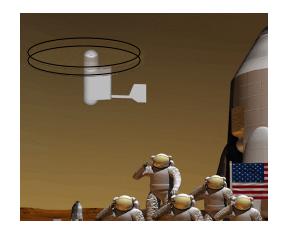
- Smart autonomous self-reconfigurable control system
- Super-safe health & usage monitoring and advanced diagnostics

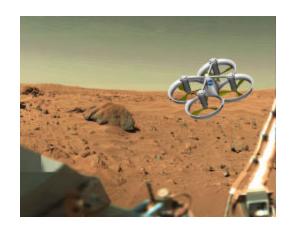
UAV Technology Expands Rotorcraft Applications

Martian autonomous rotorcraft for scout and utility roles could hunt for water and search for life











New Large Rotor Test Apparatus (LRTA)

On-line in 40 x 80 ft wind tunnel as of September 2000

- Helicopter/tilt rotor compatible
- Up to 50,000 lb thrust, 6,000 HP
- Steady/dynamic rotor balance
- Complete control system with primary and dynamic control



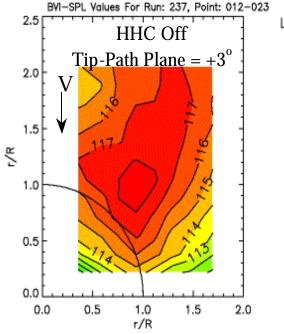


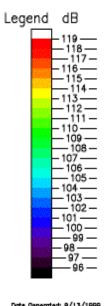
Tiltrotor Noise Reduction Breakthroughs

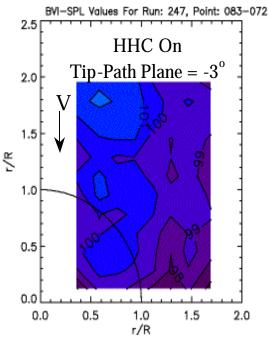
Typical reductions of 12.5 dB demonstrated in wind tunnel tests











XV-15 Low-noise Approach Profiles



RASCAL

Rotorcraft Aircrew Systems Concepts Airborne Laboratory

National In-Flight Simulation Facility for Rotorcraft and VTOL Aircraft

- programmable high bandwidth full authority flight control
- five degrees-of-freedom (programmable stabilator)
- high performance flight control processor with 160 channel analog i/o at 256 Hz and 4-channel 1553B
- evaluation pilot equipped with programmable active sidestick and programmable displays





Smart Flight Control Systems Technology

Goals:

Increase Safety

Automatically compensate for a broad spectrum of damage or failures

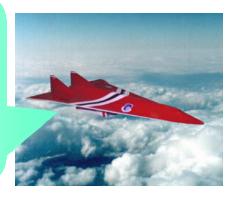
Reduce Cost

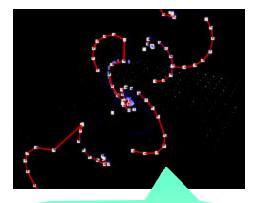
Eliminate expensive gain scheduling or explicit parameter identification

Improve Efficiency

Assist in rapid prototyping of aircraft designs

Neural flight control will be applied to new aircraft designs





High performance neural network algorithms

Neural flight control tested on modified F-15 ACTIVE aircraft





Neural flight control is being evaluated on a commercial transport simulator under nominal and failure conditions



AvSTAR

(Aviation Systems Technology Advanced Research)

Enabling Tomorrow's Air Transportation
System

Reduce separation in the terminal area

Remove restrictions across facility/sector boundaries

Improved traffic flow management



National
Traffic Flow
Management

Integrated Airspace Decision Support Tools

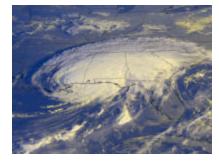
Eliminate surface congestion



Runway Productivity

Arrival/Departure
Decision Support Tools





ATM/TFM Weather Integration

Surface Congestion Alleviation

Runway Independent Aircraft Operations



AvSTAR

Runway Independent Aircraft Operations

Objectives:

- Develop technologies & criteria database that will:
 - Enable simultaneous non-interfering (SNI) A/C ops
 - Allow V/STOL aircraft to operate at airports under Cat IIIA
 - Establish ops requirements for future powered lift A/C

Benefits:

- Air traffic growth without enlarging airports
- Aviation System throughput increase & delay reduction
- Airspace safety & reliability improvement
 - Vehicles use unused & underutilized space
- National mobility & accessibility increased

Activities:

- SNI Criteria Database Development
 - Ops Concept
 - Adverse weather / low noise ops
- ATM / Aircraft Systems Integration
 - Human Centered Cockpit
 - ATM tools
- V/STOL A/C Performance / Airspace Requirements Database
- Demonstrations



Key Issues:

- Air & and infrastructure requirements
- Level I handling qualities
- Non-interfering missed approaches & guided departures
- Low noise flight paths
- SNI ops concept acceptance



Summary

- Rotorcraft can play a vital role in both civil transportation and robust military systems of the future
- This vision can be realized only with major improvements in cost, noise, all-weather reliability, and passenger acceptance
- Active system technologies, information technology, and innovative configurations are key to improving these attributes
- NASA Ames activities are aimed at enabling both the infrastructure and the air vehicles of the future